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~~How MEMS Accelerometer Gyroscope Magnetometer Work~~ \u0026 ~~Arduino Tutorial~~How accelerometer works? | Working of accelerometer in a smartphone | MEMS inside accelerometer Kalman filter test for sensor fusion (GPS + accelerometer) ~~Sensor Fusion Understanding Sensor Fusion and Tracking, Part 3: Fusing a GPS and IMU to Estimate Pose~~ Advantages and Challenges of a Multi-Sensor 3D Data Fusion Strategy Understanding Sensor Fusion and Tracking, Part 2: Fusing a Mag. Accel. \u0026 Gyro Estimate TDA Signal Processing Enables Multi-Sensor Fusion for Increased Reliability for ADAS Applications ~~Understanding Sensor Fusion and Tracking, Part 6: What Is Track-Level Fusion?~~ Sensor Fusion on Android Devices: A Revolution in Motion Processing Understanding Sensor Fusion and Tracking, Part 4: Tracking a Single Object With an IMM Filter AE 705: Learning from Aircraft Accidents : Part 2 ~~Handbook Of Multisensor Data Fusion~~ Handbook of Multisensor Data Fusion: Theory and Practice, Second Edition represents the most current concepts and theory as information fusion expands into the realm of network-centric architectures. It reflects new developments in distributed and detection fusion, situation and impact awareness in complex applications, and human cognitive concepts.

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Decentralized (or distributed) data fusion (DDF) is one of the most important areas of research in the eld of control and estimation. The motivation for decentralization is that it provides a degree of scalability and robustness that cannot be achieved using traditional centralized architectures.

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High-level data fusion is a fusion of the outcome of a model. Therefore, it may rather be termed decision fusion than data fusion. This means that blockscaling is unnecessary and the models can be...

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